

Nonlinear Potential Flow Solver Development in OpenFOAM

A. Mehmood

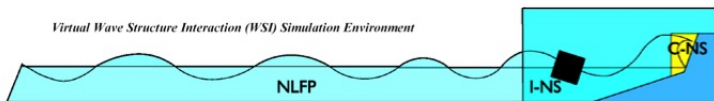
Plymouth University, UK

April 19, 2016

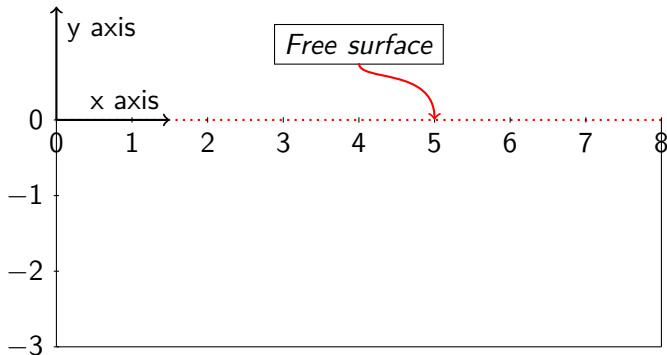
Table of Contents

- 1 Motivation
- 2 Solution Methodology
 - Mathematical Formulation
 - Sequence of the Solution Procedure
- 3 Results and Discussion
 - Standing Waves
 - Progressive Waves
- 4 Conclusions and Future Directions

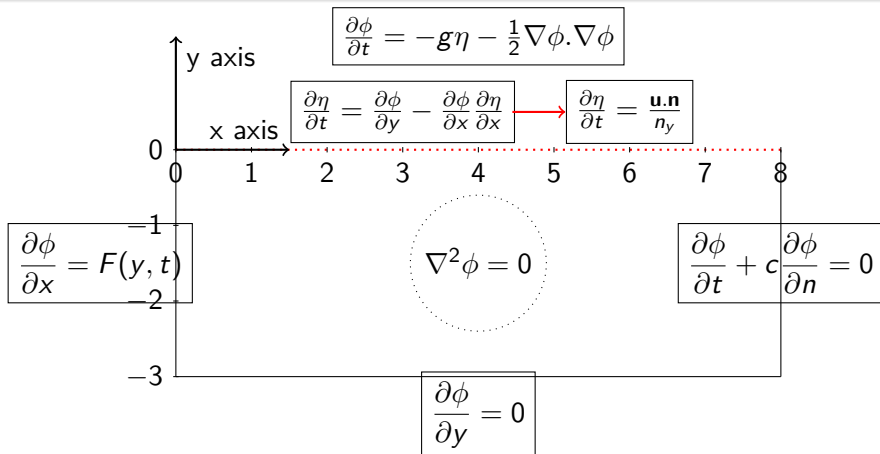
Wave Structure Interaction Simulation Environment



Wave Tank



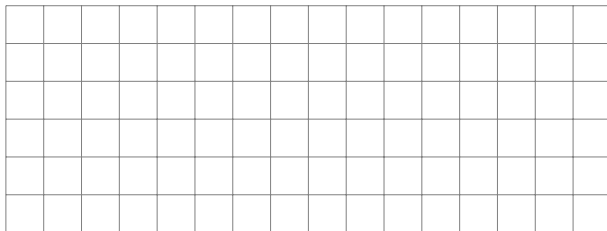
Mathematical Formulation



¹ Mayer, S, Garapon, A and Sorensen, LS (1998). "A fractional step method for unsteady free surface flow with applications to non-linear wave dynamics," *Intl J Numerical Methods in Fluids*, 28(2), 293-315

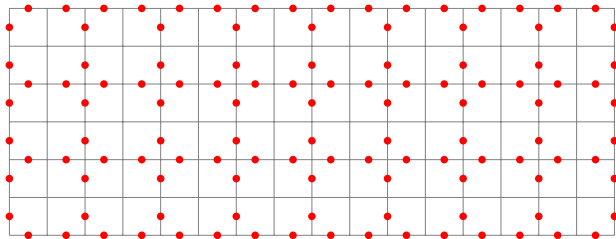
Generate the grid

- Generate the grid



Apply the boundary conditions

- Apply the boundary conditions at the face center

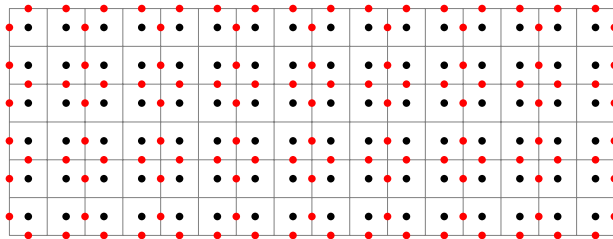


Solve Laplace's equation

- Solve Laplace's equation for the velocity potential.
- Compute the required variables (i.e., velocities $\mathbf{u} = \nabla\phi$, fluxes).

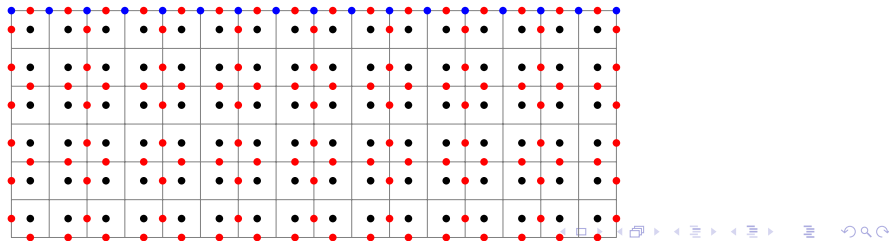
Solve Laplace's equation

- Solve Laplace's equation for the velocity potential.
- Compute the required variables (i.e., velocities $\mathbf{u} = \nabla\phi$, fluxes).



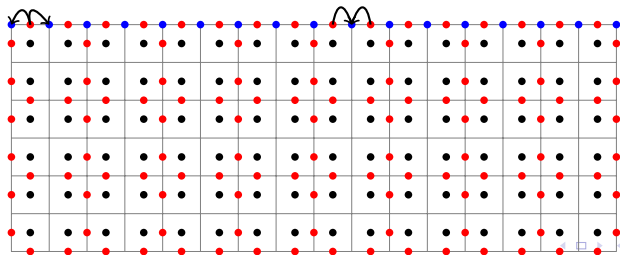
Complications of implementation of the Solver in OpenFOAM

- Simplest idea for **automatic mesh motion** in the FV framework would be to solve an equation to provide **point motion**
- However, as the FVM provides the solution in **cell centres** and motion is required on the points(vertices), this necessarily leads to **interpolation**



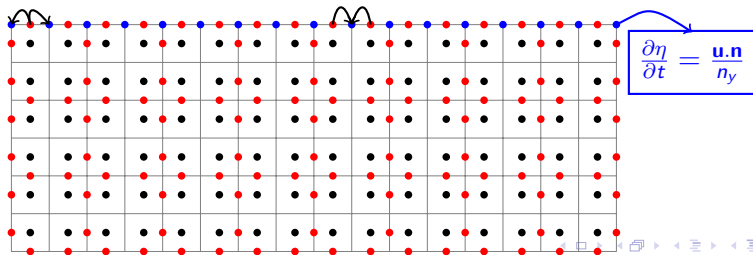
Complications of implementation of the Solver in OpenFOAM

- Simplest idea for **automatic mesh motion** in the FV framework would be to solve an equation to provide **point motion**
- However, as the FVM provides the solution in **cell centres** and motion is required on the points(vertices), this necessarily leads to **interpolation**



Complications of implementation of the Solver in OpenFOAM

- Simplest idea for **automatic mesh motion** in the FV framework would be to solve an equation to provide **point motion**
- However, as the FVM provides the solution in **cell centres** and motion is required on the points(vertices), this necessarily leads to **interpolation**



Automatic Mesh Motion in OpenFOAM

- Motion will be obtained by solving a **mesh motion equation**, where free surface motion acts as a boundary condition

Automatic Mesh Motion in OpenFOAM

- Motion will be obtained by solving a **mesh motion equation**, where free surface motion acts as a boundary condition
- **Automatic mesh motion** determines the position of **internal points** based on the free surface motion

Automatic Mesh Motion in OpenFOAM

- Motion will be obtained by solving a **mesh motion equation**, where free surface motion acts as a boundary condition
- **Automatic mesh motion** determines the position of **internal points** based on the free surface motion
- The role of **internal point motion** is to accommodate changes in the domain shape (boundary motion) and preserve the validity and quality of the mesh

Automatic Mesh Motion in OpenFOAM

- Motion will be obtained by solving a **mesh motion equation**, where free surface motion acts as a boundary condition
- **Automatic mesh motion** determines the position of **internal points** based on the free surface motion
- The role of **internal point motion** is to accommodate changes in the domain shape (boundary motion) and preserve the validity and quality of the mesh
- **Internal point motion** can be specified in a number of ways, without user interaction

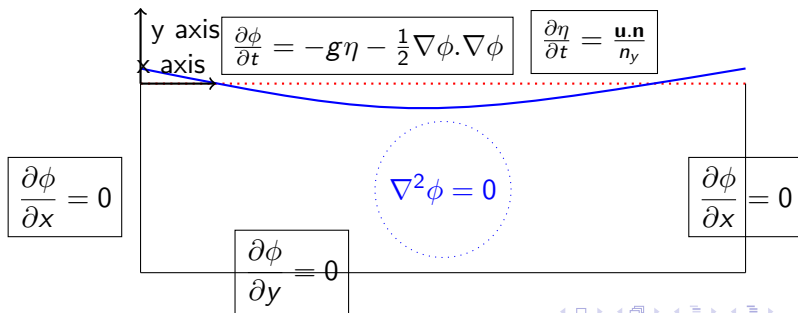
Automatic Mesh Motion in OpenFOAM

- Motion will be obtained by solving a **mesh motion equation**, where free surface motion acts as a boundary condition
- **Automatic mesh motion** determines the position of **internal points** based on the free surface motion
- The role of **internal point motion** is to accommodate changes in the domain shape (boundary motion) and preserve the validity and quality of the mesh
- **Internal point motion** can be specified in a number of ways, without user interaction
- Choices for a simplified mesh motion equation:
 - Laplace equation with constant and variable diffusivity
 - diffusivity \sim quadratic inverseDistance

Standing Waves set up

$$\eta(x, t) = a \cos(kx) \cos(\omega t) +$$

$$\frac{\pi a^2}{\lambda} \left[\cos^2(\omega t) - \frac{1}{4 \cosh^2(kH)} + \frac{3 \cos(2\omega t)}{4 \sinh^2(kH)} \right] \cos(2kx) \quad (1)$$



Time Histories of Wave Elevation

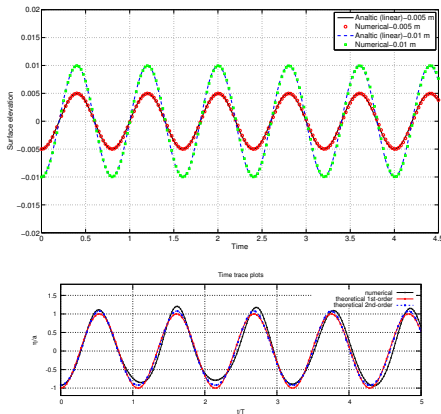


Figure: Time history of free surface elevation at the centre of the domain

Variation of wave period

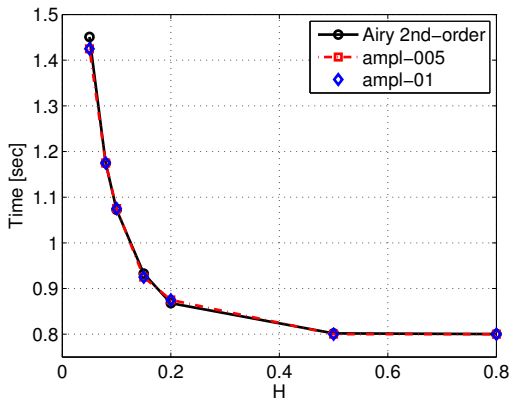
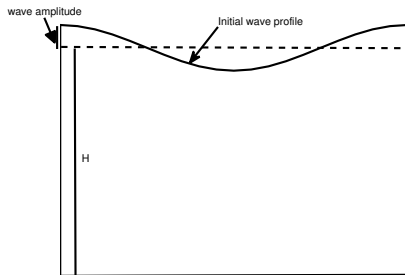
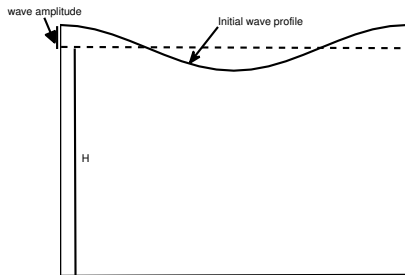
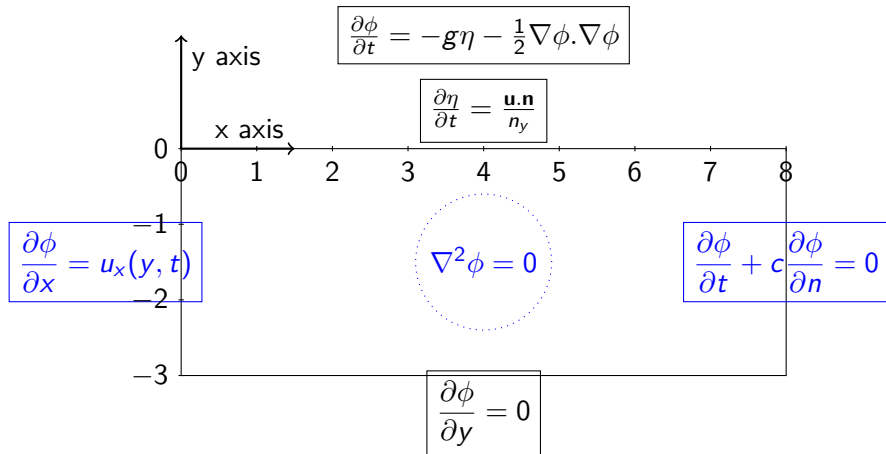


Figure: Variation of wave period against mean water depth normalized by wavelength

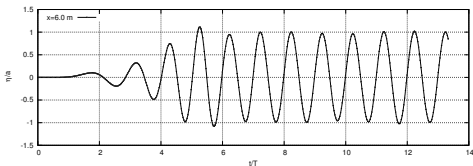
Standing Wave Animation



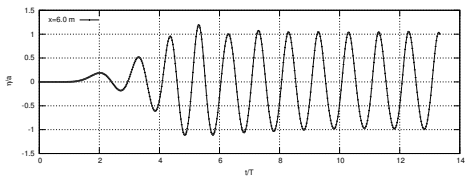
Progressive Waves set up



Progressive Waves



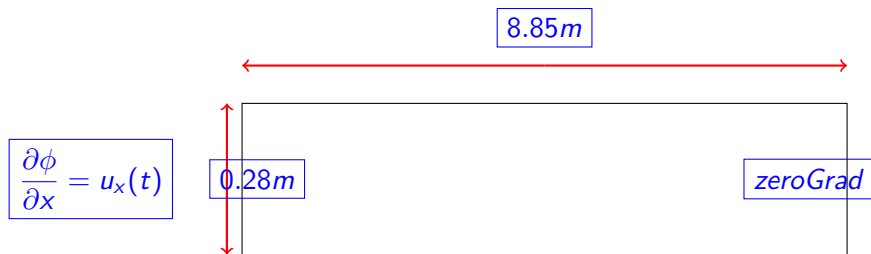
(a) $a = 0.01$ m, $H = 1.5$ m, $T = 1.5$ s



(b) $a = 0.06$ m, $H = 1.0$ m, $T = 1.5$ s.

Figure: Time history of free surface elevation at location $x = 6.0$ m (from inlet boundary)

Comparison with Experiment (F.Gao-2003)



¹ Gao, F, (2003). "An efficient finite element technique for free surface flow," Ph.D. thesis, Brighton University, UK.

Comparison with Experiment (F.Gao-2003)

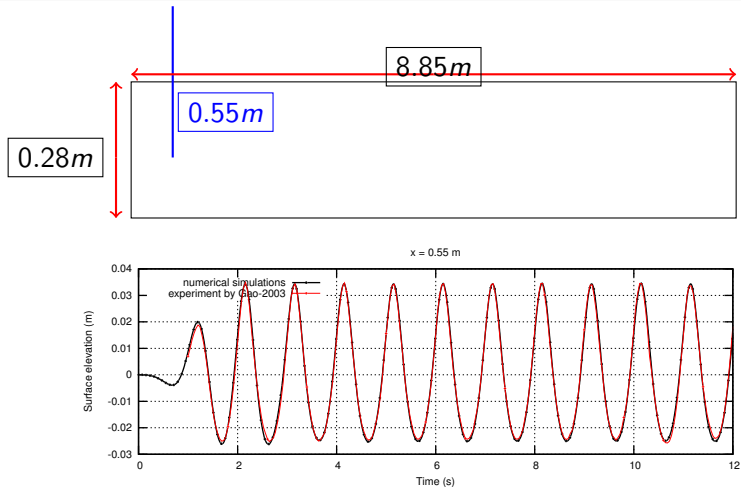


Figure: Time history of wave elevation at location $x = 0.55\text{ m}$.

Comparison with Experiment (F.Gao-2003)

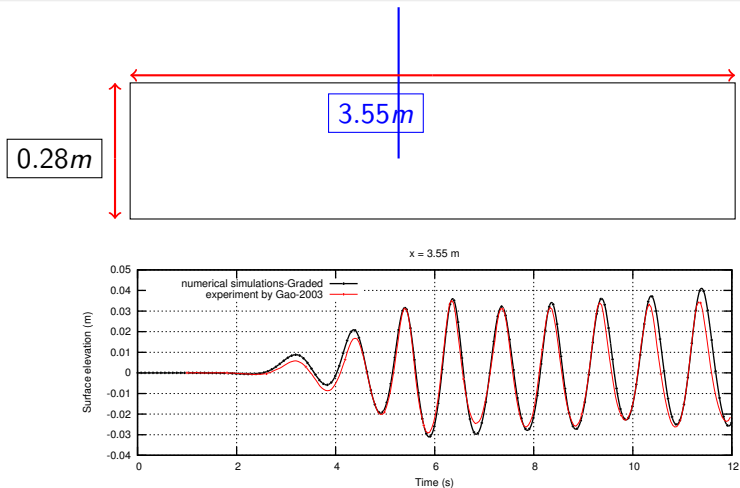


Figure: Time history of wave elevation at location $x = 3.55\text{ m}$.

Comparison with Experiment (F.Gao-2003)

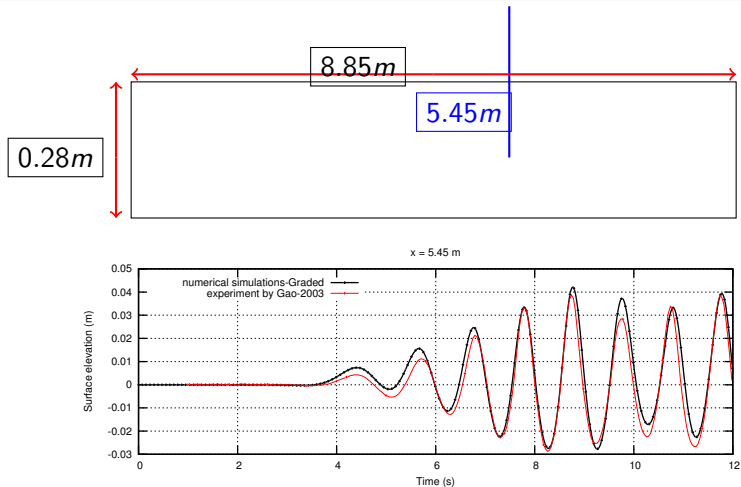
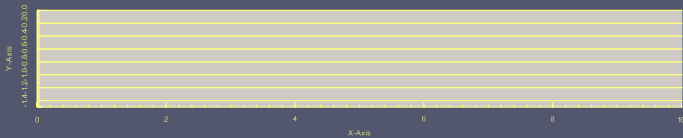


Figure: Time history of wave elevation at location $x = 5.45\text{ m}$.

Comparison with experiment



Conclusions and Future Directions

- Developed a free surface tracking solver for numerical simulation of unsteady irrotational fully non-linear water waves

Conclusions and Future Directions

- Developed a free surface tracking solver for numerical simulation of unsteady irrotational fully non-linear water waves
- The solver has been validated by application to a number of test cases, ranging from shallow water standing waves to different wave amplitudes progressive waves

Conclusions and Future Directions

- Developed a free surface tracking solver for numerical simulation of unsteady irrotational fully non-linear water waves
- The solver has been validated by application to a number of test cases, ranging from shallow water standing waves to different wave amplitudes progressive waves
- **Solution of Laplace's equation for the velocity potential, the non-linear free surface boundary conditions, the wave generation and the absorption boundary conditions** are all not part of the standard OpenFOAM® distribution

Conclusions and Future Directions

- Developed a free surface tracking solver for numerical simulation of unsteady irrotational fully non-linear water waves
- The solver has been validated by application to a number of test cases, ranging from shallow water standing waves to different wave amplitudes progressive waves
- **Solution of Laplace's equation for the velocity potential, the non-linear free surface boundary conditions, the wave generation and the absorption boundary conditions** are all not part of the standard OpenFOAM® distribution
- **Coupling to available Navier-Stokes solvers in OpenFOAM®**

Conclusions and Future Directions

- Developed a free surface tracking solver for numerical simulation of unsteady irrotational fully non-linear water waves
- The solver has been validated by application to a number of test cases, ranging from shallow water standing waves to different wave amplitudes progressive waves
- **Solution of Laplace's equation for the velocity potential, the non-linear free surface boundary conditions, the wave generation and the absorption boundary conditions** are all not part of the standard OpenFOAM® distribution
- **Coupling to available Navier-Stokes solvers in OpenFOAM®**
- **The developed solver and the associated boundary conditions will be released as an open-source for the marine and offshore community**

Thank you